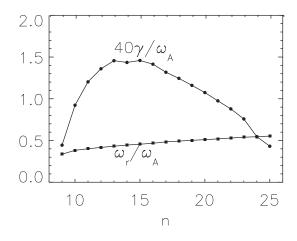
# Progress and plans for particle based kinetic MHD closures

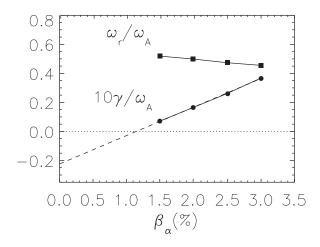
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## TAE calculation of ITER hot alpha critical beta using GEM code

Gyrokinetic core ions and hot alphas Drift-fluid electrons Shaped equilibrium

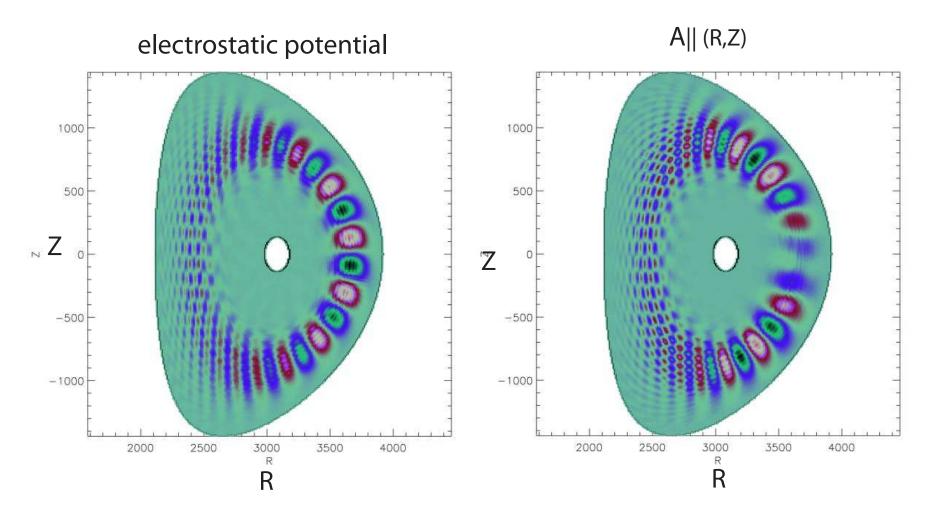




 $\omega-$  n scan for  $\beta_{\alpha}(0)=3\%$ .

 $\gamma$  peaks at n = 15.

n=15 instability threshold is about  $\beta_{\alpha c}=1.1\%$ .



n=10

#### **Recent CEMM publications**

"Low-noise particle algorithms for extended MHD closure," D. Barnes, J. Cheng, S. Parker, *Phys. Plasmas* **15** 055702 (2008)

"Particle-in-cell simulation with Vlasov ions and drift kinetic electrons," Y. Chen, S. Parker, Phys. Plasmas **16** 052305 (2009)

"Gyrokinetic delta-f particle simulation of the TAE,"
J. Lang, Y. Chen, S. Parker, G. Fu, Phys. Plasmas **16** 052305 (2009)

Expect current/future work (Jianhua Cheng's Ph.D. thesis) will result in two additional publications. One on the second order implicit algorithm and one on reconnection with fully kinetic ions.

# **CEMM Proposed work**

- 1. Develop drift kinetic electron model for closure of hybrid model.
  - Test model on slab tearing mode problem.
- 2. Implement kinetic MHD model in NIMROD code.
- 3. Simulate classical tearing mode in toroidal geometry with GEM and compare with M3D two-fluid (drift ordering). Verification of M3D two-fluid model. In collaboration with L. Sugiama.
- 4. Initialize NIMROD with  $\delta E$  and  $\delta B$  from GEM electromagnetic turbulence simulations to see if tearing parity perturbations zonal fields can seed NTMs. In collaboration with S. Kruger.

#### Motivations

- In certain problems, such as Tokamak edge ETG and weak guide field (or no guide field) magnetic reconnection, the gyro-kinetic orderings are not valid. Therefore the current gyro-kinetic model should be extended.
- Also, for GEM turbulence code on small devices like NSTX, the timestep constraint is  $\Omega_i \Delta t < 0.2$ .
- If electrons and ions are treated as fluid and full-kinetic particles respectively, this simple hybrid model could include the kinetic ion physics and capture MHD physics in a natural way. Meanwhile, realistic electron ion mass ratio could be preserved. It will also serve as a good check for the validity of gyro-kinetic model in the edge.
- We are using the GEM code as a test bed for the model and algorithm. To include kinetic electron effects, drift-kinetic and gyro-kinetic electrons could be added.

#### Lorentz ion and fluid electron model

• Lorentz force ions:

$$egin{aligned} rac{doldsymbol{v}_i}{dt} &= rac{q}{m_i}(oldsymbol{E} + oldsymbol{v}_i imes oldsymbol{B}) \ rac{doldsymbol{x}_i}{dt} &= oldsymbol{v}_i \end{aligned}$$

• Isothermal fluid electrons as a simple test:

$$\delta P_e = \gamma \delta n_e T_e$$

I am working on drift-kinetic and will add gyrokinetic electrons.

• Ampere's law:

$$\nabla \times \boldsymbol{B} = \mu_0 e \left( n_i \boldsymbol{u}_i - n_e \boldsymbol{u}_e \right)$$

• Faraday's law

$$\nabla \times \boldsymbol{E} = -\frac{\partial \, \boldsymbol{B}}{\partial t}$$

#### Generalized Ohm's law

• Starting from the electron momentum equation:

$$en_e(\boldsymbol{E} + \boldsymbol{u}_e \times \boldsymbol{B}) = en_e \eta \, \boldsymbol{j} - \nabla \cdot \boldsymbol{\Pi}_e - m_e \, \frac{\partial (n_e \boldsymbol{u}_e)}{\partial t}$$

where  $\Pi_e = \int f_e m_e \boldsymbol{v} \boldsymbol{v} d\boldsymbol{v}$ .

• Substitute in Ampere's law  $\mathbf{j} = e(n_i \mathbf{u}_i - n_e \mathbf{u}_e) = \frac{1}{\mu_0} \nabla \times \mathbf{B}$ , we could rewrite the above equation as

$$en_e \mathbf{E} = -\mathbf{j}_i \times \mathbf{B} + \frac{1}{\mu_0} (\nabla \times \mathbf{B}) \times \mathbf{B} + \frac{en_e}{\mu_0} \eta (\nabla \times \mathbf{B}) - \nabla \cdot \mathbf{\Pi}_e - m_e \frac{\partial (n_e \mathbf{u}_e)}{\partial t}$$
  
where  $\mathbf{j}_i = en_i \mathbf{u}_i$ 

• Taking time derivative of Ampere's law

$$\mu_0 e(\frac{\partial n_i \boldsymbol{u}_i}{\partial t} - \frac{\partial n_e \boldsymbol{u}_e}{\partial t}) = \nabla \times \frac{\partial \boldsymbol{B}}{\partial t} = -\nabla \times \nabla \times \boldsymbol{E}$$

The first term on the left hand side comes from ion momentum equation

$$m_i \frac{\partial n_i \boldsymbol{u}_i}{\partial t} = e n_i (\boldsymbol{E} + \boldsymbol{u}_i \times \boldsymbol{B}) - \nabla \cdot \boldsymbol{\Pi}_i$$

the electron inertial term could be written as

$$m_e \frac{\partial (n_e \boldsymbol{u}_e)}{\partial t} = \frac{m_e}{m_i} \left( e n_i (\boldsymbol{E} + \boldsymbol{u}_i \times \boldsymbol{B}) - \nabla \cdot \boldsymbol{\Pi}_i \right) + \frac{m_e}{\mu_0 e} \nabla \times (\nabla \times \boldsymbol{E})$$

• Dropping terms with  $m_e/m_i$ , we arrive at the generalized Ohm's law

$$\boldsymbol{E} + \frac{c^2}{w_{pe}^2} \nabla \times (\nabla \times \boldsymbol{E}) = -\frac{1}{en_e} \boldsymbol{j}_i \times \boldsymbol{B} + \frac{1}{\mu_0 en_e} (\nabla \times \boldsymbol{B}) \times \boldsymbol{B} + \frac{\eta}{\mu_0} \nabla \times \boldsymbol{B} - \frac{\nabla \cdot \boldsymbol{\Pi}_e}{en_e}$$

# Implicit $\delta f$ algorithm

• Given an ion distribution function  $f_i = f_{i0} + \delta f_i$ , utilizing the usual  $\delta f$  method, the weight equation is

$$\frac{d}{dt}w_i = -\frac{d\ln f_{i0}}{dt}$$

- For  $\rho_i$  scale instabilities  $k_{\perp}\rho_i \sim 1, \beta \sim 0.01$ , the compressional wave frequency  $\frac{\omega}{\Omega_i} \geq 10$ , therefore  $\Omega_i \Delta t \ll 0.01$  is needed. To get rid of the fast frequency, we employ an implicit scheme.
- A first-order scheme has been developed. Here we come up with a second-order scheme with an adjustable centering parameter and improved the field solver.

## Second order implicit scheme

• Particle push

$$\frac{\boldsymbol{x}^{n+1} - \boldsymbol{x}^{n}}{\Delta t} = (1 - \theta) \, \boldsymbol{v}^{n} + \theta \, \boldsymbol{v}^{n+1}$$

$$\frac{\boldsymbol{v}^{n+1} - \boldsymbol{v}^{n}}{\Delta t} = \frac{q}{m} \left( (1 - \theta) \, (\boldsymbol{E}^{n} + \boldsymbol{v}^{n} \times \boldsymbol{B}^{n}) + \theta \, (\boldsymbol{E}^{n+1} + \boldsymbol{v}^{n+1} \times \boldsymbol{B}^{n+1}) \right)$$

$$\frac{\boldsymbol{w}^{n+1} - \boldsymbol{w}^{n}}{\Delta t} = \frac{q}{T_{i0}} \left( (1 - \theta) \, (\boldsymbol{E}^{n} \cdot \boldsymbol{v}^{n}) + \theta \, (\boldsymbol{E}^{n+1} \cdot \boldsymbol{v}^{n+1}) \right)$$

• Faraday's law

$$\frac{\delta \boldsymbol{B}^{n+1} - \delta \boldsymbol{B}^n}{\Delta t} = -[(1 - \theta) \ \nabla \times \boldsymbol{E}^n + \theta \ \nabla \times \boldsymbol{E}^{n+1}]$$

• Ohm's law:

$$(n_{e0} + \boldsymbol{\delta n_e})\boldsymbol{E}^{n+1} + \frac{m_e}{\mu_0 e} \nabla \times (\nabla \times \boldsymbol{E}^{n+1}) = -\delta \boldsymbol{j}_i^{n+1} \times \boldsymbol{B}_0 - \delta \boldsymbol{j}_i^{n+1} \times \delta \boldsymbol{B}^{n+1} + \frac{1}{\mu_0} (\nabla \times \delta \boldsymbol{B}^{n+1}) \times \boldsymbol{B}_0$$

$$+ \frac{1}{\mu_0} (\nabla \times \boldsymbol{B}_0) \times \delta \boldsymbol{B}^{n+1} + \frac{1}{\mu_0} (\nabla \times \delta \boldsymbol{B}^{n+1}) \times \delta \boldsymbol{B}^{n+1}$$

$$+ \frac{\eta e n_{e0}}{\mu_0} \nabla \times \delta \boldsymbol{B}^{n+1} + \frac{\eta e \delta n_e}{\mu_0} \nabla \times \delta \boldsymbol{B}^{n+1} - \gamma T_e \nabla \delta n_i^{n+1}$$

#### Ion current

• First half push cycle

$$\mathbf{v}^{\star} = \mathbf{v}^{n} + (1 - \theta)\Delta t \frac{q}{m} (\mathbf{E}^{n} + \mathbf{v}^{n} \times \mathbf{B}^{n})$$

$$\mathbf{x}^{\star} = \mathbf{x}^{n} + (1 - \theta)\Delta t \mathbf{v}^{n}$$

$$\mathbf{v}^{\star} = \mathbf{w}^{n} + (1 - \theta)\Delta t \frac{q}{T_{i0}} (\mathbf{E}^{n} \cdot \mathbf{v}^{n})$$

• Dependence of  $\delta \boldsymbol{j}_i^{n+1}$  on  $\boldsymbol{E}^{n+1}$ 

$$\delta \boldsymbol{j}_{i}^{n+1} = q \sum_{j} w_{j}^{n+1} \boldsymbol{v}_{j}^{n+1}$$

$$= \delta \boldsymbol{j}_{i}^{\star} + \theta \Delta t \frac{V}{N} \sum_{j} \frac{1}{\Delta V} \frac{q}{T_{i}} \boldsymbol{v}_{j} \boldsymbol{E}^{n+1} (\boldsymbol{x}_{j}^{n+1}) \cdot \boldsymbol{v}_{j} S(\boldsymbol{x} - \boldsymbol{x}_{j}^{n+1})$$

$$\simeq \delta \boldsymbol{j}_{i}^{\star} + \theta \Delta t \frac{q^{2}}{m} \boldsymbol{E}^{n+1} \equiv \boldsymbol{J}_{i}^{\prime}$$

where this equation follows as the marker distribution is Maxwellian.

• For accuracy issues, we iterate on the differences between  $\delta \boldsymbol{j}_i^{n+1}$  and  $\boldsymbol{J}_i'$  while solving Ohm's law to obtain  $\boldsymbol{E}^{n+1}$ .

• Once we have  $\mathbf{E}^{n+1}$ ,  $\delta \mathbf{B}^{n+1}$  is advanced according to the Faraday's law.

$$\frac{\delta \boldsymbol{B}^{n+1} - \delta \boldsymbol{B}^n}{\Delta t} = -[(1 - \theta) \ \nabla \times \boldsymbol{E}^n + \theta \ \nabla \times \boldsymbol{E}^{n+1}]$$

ullet With  $m{E}^{n+1}$  and  $\delta m{B}^{n+1}$ , we could proceed to complete the second half push cycle

$$\mathbf{v}^{n+1} = \mathbf{v}^* + \theta \Delta t \, \frac{q}{m} \left( \mathbf{E}^{n+1} + \mathbf{v}^{n+1} \times \mathbf{B}^{n+1} \right)$$

$$\mathbf{x}^{n+1} = \mathbf{x}^* + \theta \Delta t \, \mathbf{v}^{n+1}$$

$$\mathbf{v}^{n+1} = \mathbf{v}^* + \theta \Delta t \, \frac{q}{T_{i0}} \left( \mathbf{E}^{n+1} \cdot \mathbf{v}^{n+1} \right)$$

#### Field solver

• Zero-order B field

$$\boldsymbol{B}_0 = \boldsymbol{e}_y \boldsymbol{B}_{0y} + \boldsymbol{e}_z \boldsymbol{B}_{0z}.$$

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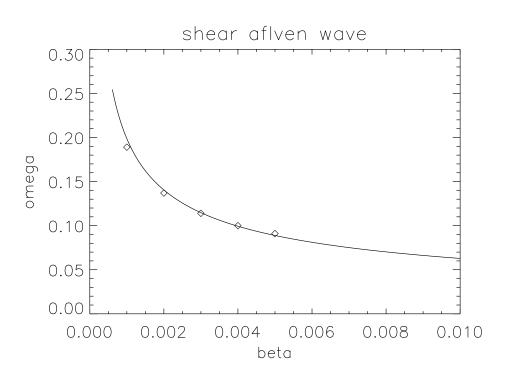
• In the Ohm's law,

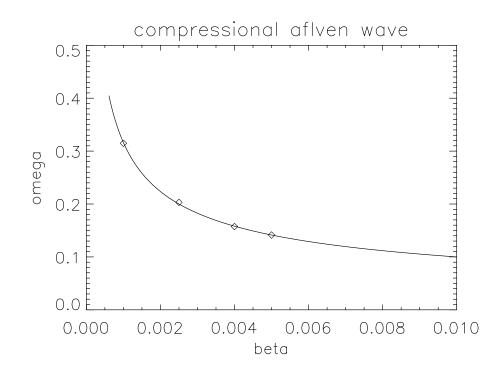
$$n_e \, \boldsymbol{E}^{n+1} + \frac{n_e}{\beta_e} (\frac{m_e}{m_i} + \theta \Delta t \eta) \, \nabla \times (\nabla \times \boldsymbol{E}^{n+1}) + \theta \, \frac{\Delta t}{\beta_e} \, (\nabla \times \nabla \times \boldsymbol{E}^{n+1}) \times \boldsymbol{B}_0 + \cdots$$
$$= -\delta \boldsymbol{j}_i^{n+1} \times \boldsymbol{B}_0 + \cdots$$

the third term on the left hand side involves the cross product of  $\boldsymbol{E}^{n+1}$  and  $\boldsymbol{B}_0,$ 

- If  $\mathbf{B}_0$  is space-dependent, we could not obtain a clean single mode equation through Fourier transformation. As in the Harris sheet equilibrium,  $\mathbf{B}_0$  only depends on x, we could Fourier transform  $\mathbf{E}^{n+1}(x,y,z)$  to  $\mathbf{E}^{n+1}(x,k_y,k_z)$  and solve the latter by direct matrix inversion for every  $k_y, k_z$  mode.

#### 3-D Shearless Slab Alfven waves





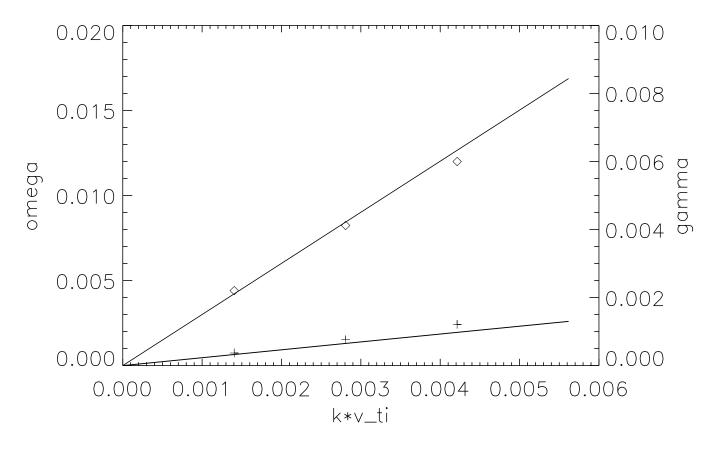
 $2 \times 32 \times 32$  grids, 131072 particles.

For shear Alfven wave,  $k_{\perp} = 0$ ,  $k_{\parallel} \rho_i = 0.00628$ , initialize with  $\delta \boldsymbol{B}_{\perp}$ .

For compressional Alfven wave,  $k_{\parallel} = 0$ ,  $k_{\perp} \rho_i = 0.01$ , initialize with  $\delta \boldsymbol{B}_{\parallel}$ .

These simulations are done in a tilted  $B_0$  field.

### Ion acoustic wave



 $2 \times 32 \times 32$  grids, 131072 particles.  $k_{\perp} = 0$ .

#### Whistler wave

• By neglecting ion current and electron inertia, the Ohm's law yields

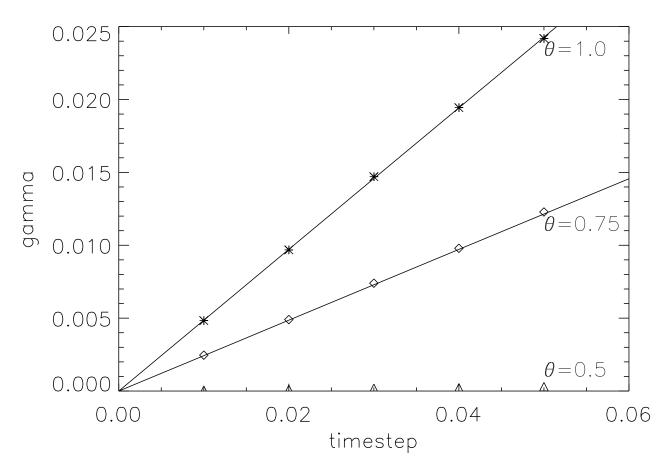
$$\boldsymbol{E} = \frac{1}{\beta_e} (\nabla \times \delta \boldsymbol{B}) \times \boldsymbol{B}_0.$$

• The numerical dispersion relation from a Von Neumann stability analysis

$$\tan(\omega_r \Delta t) = \frac{\frac{k^2}{\beta} \Delta t}{1 - (\frac{k^2}{\beta} \Delta t)^2 \theta (1 - \theta)}$$

$$\omega_i \Delta t = -\frac{1}{2} \ln \left( \frac{\left(1 - (\frac{k^2}{\beta} \Delta t)^2 \theta (1 - \theta)\right)^2 + (\frac{k^2}{\beta} \Delta t)^2}{\left(1 + (\frac{k^2}{\beta} \Delta t)^2 (1 - \theta)^2\right)^2} \right)$$

# Numerical dispersion relation



 $16 \times 16 \times 32$  grids, 131072 particles,  $k_{\perp} = 0, k_{\parallel} \rho_i = 0.0628, \beta = 0.004$ .

# Harris sheet equilibrium

• Zero-order **B** 

$$\boldsymbol{B}_0(\boldsymbol{x}) = B_{y0} \tanh(\frac{x}{L}) \, \hat{\boldsymbol{y}} + B_G \, \hat{\boldsymbol{z}}$$

• The equilibrium distribution function is

$$f_{0s} = n_h \operatorname{sech}^{2}(\frac{x}{L}) \left(\frac{2\pi T_s}{m_s}\right)^{-\frac{3}{2}} \exp\left[-\frac{m(v_x^2 + v_y^2 + (v_z - v_{ds})^2)}{2T_s}\right] + n_b \left(\frac{2\pi T_s}{m_s}\right)^{-\frac{3}{2}} \exp\left(-\frac{mv^2}{2T_s}\right)$$

• Load particles as Maxwellian

$$g_s = n_0 \left(\frac{2\pi T_s}{m_s}\right)^{-\frac{3}{2}} \exp\left(-\frac{m_s \mathbf{v}^2}{2T_s}\right)$$

• Weight equation

$$\frac{dw_i}{dt} = \frac{q_s}{T_s} \left( \mathbf{E} \cdot \mathbf{v} \left( \frac{f_h}{g_s} + \frac{n_b}{n_0} \right) - \mathbf{v}_d \cdot \left( \mathbf{E} + \mathbf{v} \times \delta \mathbf{B} \right) \frac{f_h}{g_s} \right) 
\frac{f_h}{g_s} = \frac{n_h}{n_0} \operatorname{sech} \left( \frac{x}{L} \right)^2 \exp \left( \frac{m_s}{2T_s} \left( 2\mathbf{v}_d \cdot \mathbf{v} - \mathbf{v}_d^2 \right) \right).$$

# **Boundary conditions**

• Perfect conducting wall boundary condition is employed in x while periodic boundary conditions in y and z direction.

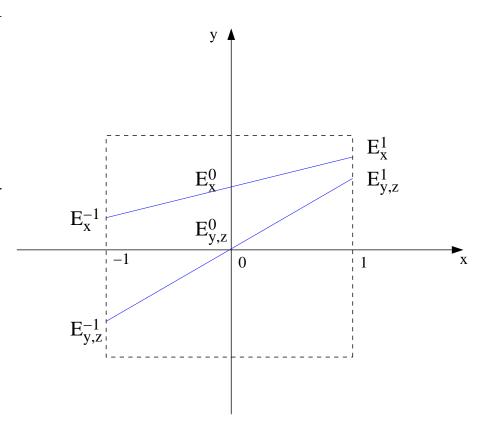
$$\mathbf{E}_{y,z}|_{x=\pm l_x/2} = 0$$
$$\delta \mathbf{B}_x|_{x=\pm l_x/2} = 0$$

ullet Numerically, the boundary condition for  $oldsymbol{E}$  can be treated as

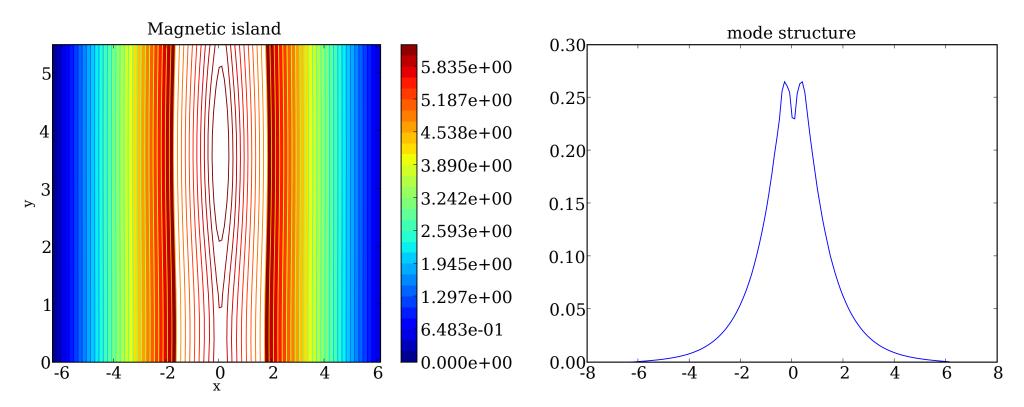
$$\frac{\mathbf{E}_{y,z}^{-1} + \mathbf{E}_{y,z}^{1}}{2} = 0$$
$$\frac{\mathbf{E}_{x}^{-1} + \mathbf{E}_{x}^{1}}{2} = \mathbf{E}_{x}^{0}$$

at 
$$x = \pm l_x/2$$
.

• Boundary condition for  $\delta \boldsymbol{B}$  is assumed in Faraday's equation.



## Resistive Tearing mode



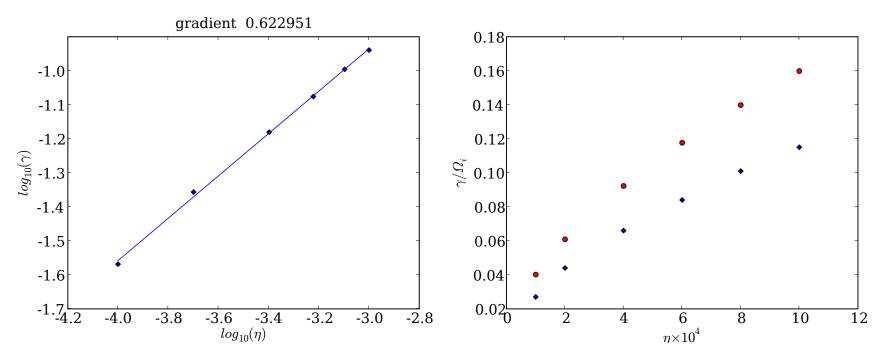
$$128 \times 16 \times 4$$
 grids, 131072 particles.  $k_y \rho_i = 1, \frac{L}{\rho_i} = 0.25, \beta_e = \frac{\mu_0 n_0 T_e}{B_0^2} = 0.2,$ 

$$\eta_{\overline{B_0}}^{en_0} = 0.0008, \frac{\mathbf{B}_G}{B_0} = 2, \frac{T_i}{T_e} = 1, \frac{l_x}{\rho_i} = 12.56, \frac{l_y}{\rho_i} = 6.28$$

## Tearing mode growth rate

• Linear Tearing mode theory shows that the growth rate is (scaled)

$$\gamma = 0.55 \left(\frac{\Delta'}{\beta}\right)^{4/5} \eta^{3/5} (k B'_{y0})^{2/5}.$$



$$256 \times 16 \times 4$$
 grids, 131072 particles.  $k_y \rho_i = 0.5, \frac{L}{\rho_i} = 0.4, \beta_e = \frac{\mu_0 n_0 T_e}{B_0^2} = 0.2,$   
 $\frac{\mathbf{B}_G}{B_0} = 1, \frac{T_i}{T_e} = 1, \frac{l_x}{\rho_i} = 12.8, \frac{l_y}{\rho_i} = 12.56$ 

# The Lorentz ion/Drift kinetic electron model

Lorentz ions:

$$\frac{d\mathbf{v}_i}{dt} = \frac{q}{m_i}(\mathbf{E} + \mathbf{v}_i \times \mathbf{B}), \qquad \frac{d\mathbf{x}_i}{dt} = \mathbf{v}_i$$

Drift kinetic electrons:  $\varepsilon = \frac{1}{2}m_e v^2$ 

$$\frac{d\mathbf{x}}{dt} = \mathbf{v}_G \equiv v_{\parallel} \left( \mathbf{b} + \frac{\delta \mathbf{B}_{\perp}}{B_0} \right) + \mathbf{v}_D + \mathbf{v}_E$$
$$\frac{d\varepsilon}{dt} = -e\mathbf{v}_G \cdot \mathbf{E} + \mu \frac{\partial B}{\partial t}, \quad \frac{d\mu}{dt} = 0$$

Ampere's equation

$$\nabla \times \mathbf{B} = \mu_0 (\mathbf{J}_i - e n_e (\mathbf{V}_{e\perp} + u_{\parallel e} \mathbf{b}))$$

$$\mathbf{V}_{\mathrm{e}\perp} = \frac{1}{B}\mathbf{E} \times \mathbf{b} - \frac{1}{enB}\mathbf{b} \times \nabla P_{\perp \mathrm{e}}$$

$$\mathbf{J}_{i} = \int f_{i}\mathbf{v} \, d\mathbf{v}, \quad u_{\parallel \mathrm{e}} = \int f_{e} \, v_{\parallel} \, d\mathbf{v}, \quad P_{\perp \mathrm{e}} = \int f_{e} \frac{1}{2} m_{e} v^{2} \, d\mathbf{v}$$

Faraday's equation,

$$\frac{\partial \mathbf{B}}{\partial t} = -\nabla \times \mathbf{E}$$

- The Harris sheet equilibrium distribution function is a drifted Maxwellian with a non-uniform density profile in x, which doesn't meet the drift-kinetic assumptions. If a strong guide field in z exists, the nonuniformity could be treated as a perturbation, then the drift-kinetic equations is appliable in this case.
- With drift-kinetic electrons, we could study the roles of kinetic electrons in reconnection problem by making direct comparison with our fluid electron model.
- Currently I am adding the drift-kinetic electrons into the code.

# Including gyrokinetic electrons

• Gyrokinetic equations are usually derived in terms of **A** and  $\phi$ , to make explicit the ordering

$$\frac{\partial \mathbf{A}}{\partial t} \sim \epsilon_{\delta} \nabla_{\perp} \phi$$

• The Frieman-Chen gyrokinetic equation, assuming isotropy  $(\partial F_0/\partial \mu = 0)$ ,

$$\hat{L}_g \delta H_0 \equiv \left(\frac{\partial}{\partial t} + v_{\parallel} \mathbf{b} \cdot \nabla + \mathbf{v}_D \cdot \nabla\right) \delta H_0 = -\frac{q}{m} (S_L + \langle R_{\rm NL} \rangle),$$

where  $\delta H_0$  is related to the perturbed distribution  $\delta F$  through  $\delta F = \frac{q}{m} \phi \frac{\partial F_0}{\partial \epsilon} + \delta H_0$ 

$$S_L = \frac{\partial}{\partial t} \langle \phi - \mathbf{v} \cdot \mathbf{A} \rangle \frac{\partial F_0}{\partial \epsilon} - \nabla \langle \phi - \mathbf{v} \cdot \mathbf{A} \rangle \times \frac{\mathbf{b}}{\Omega} \cdot \nabla F_0,$$

$$\langle R_{\rm NL} \rangle = -\nabla \langle \phi - \mathbf{v} \cdot \mathbf{A} \rangle \times \frac{\mathbf{b}}{\Omega} \cdot \nabla \delta H_0.$$

• Define  $\delta f = \frac{q}{m} \langle \phi \rangle \frac{\partial F_0}{\partial \epsilon} + \delta H_0$ . The gyrokinetic equation for  $\delta f$  is, written in terms of  $\mathbf{E}_1$  and  $\mathbf{B}_1$ 

$$\frac{D}{Dt}\delta f = -\left(\frac{1}{B_0}\langle \mathbf{E}_1 \rangle \times \mathbf{b} + v_{\parallel} \frac{\langle \mathbf{B}_{1\perp} \rangle}{B_0}\right) \cdot \nabla F_0 + \frac{1}{m} \dot{\epsilon} \frac{\partial F_0}{\partial \epsilon}$$

$$\frac{D}{Dt} = \hat{L}_g + \left(\frac{1}{B_0} \langle \mathbf{E}_1 \rangle \times \mathbf{b} + v_{\parallel} \frac{\langle \mathbf{B}_{1 \perp} \rangle}{B_0}\right) \cdot \nabla, \qquad \dot{\epsilon} = q \left(v_{\parallel} \mathbf{b} + \mathbf{v}_D + v_{\parallel} \frac{\langle \mathbf{B}_{1 \perp} \rangle}{B_0}\right) \cdot \langle \mathbf{E}_1 \rangle + q \langle \mathbf{v}_{\perp} \cdot \mathbf{E}_{1 \perp} \rangle$$

• The perturbed electron diamagnetic flow comes from  $\delta f$ ,

$$n_0 \mathbf{V}_D(\mathbf{x}) = \int (v_{\parallel} \mathbf{b} + \mathbf{v}_{\perp}(\mathbf{R}', \epsilon, \mu, \alpha)) \delta f(\mathbf{R}', \epsilon, \mu) \delta(\mathbf{x} - \mathbf{R}' - \boldsymbol{\rho}) J d\mathbf{R}' d\epsilon d\mu d\gamma$$

 $n_0 \mathbf{V}_D$  is computed by depositing the particle current along the gyro-ring. In the drift-kinetic limit  $\mathbf{V}_D$  reduces to the electron diamagnetic flow.

• The electron  $\mathbf{E} \times \mathbf{B}$  flow comes from the first term in  $\delta F$ ,

$$n_0 \mathbf{V}_E(\mathbf{x}) = \frac{\mathbf{q}}{\mathbf{m}} \int \mathbf{v} \left( \phi(\mathbf{x}) - \langle \phi \rangle \left( \mathbf{x} - \boldsymbol{\rho}, \epsilon, \mu \right) \right) \frac{\partial \mathbf{F_0}}{\partial \epsilon} \mathbf{J} \, \mathbf{d} \epsilon \, \mathbf{d} \mu \, \mathbf{d} \gamma$$

in eikonal form,

$$n_0 \mathbf{V}_E = n_0 \frac{h}{B_0} \delta \mathbf{E}_k \times \mathbf{b}$$

with  $b = k_{\perp}^2 v_T^2 / \Omega^2$  and

$$h(b) = -\frac{1}{b^2} \int_0^\infty e^{-x^2/2b} J_0(b) J_0'(b) x^2 dx$$

In the limit of small  $k\rho \ll 1$  the factor h(b) become unity, so that  $n_0 \mathbf{V}_E$  become the total guiding center  $\mathbf{E} \times \mathbf{b}$  flow.

## Summary

- 1. We implemented an implicit algorithm with Lorentz force ions and isothermal fluid electrons which is
  - Quasi-neutral and fully electromagnetic.
  - Suitable for MHD scale plasmas.
- 2. Second order implicit scheme allows bigger time step,  $\Omega_i \Delta t \gtrsim 0.1$ .
  - Compared the first order and second order scheme with Whistler waves
- 3. Demonstrated 3-D slab simulation for compressional and shear Alfven waves, Whistler wave, and the ion acoustic wave.
- 4. With conducting wall boundary condition on x and periodic boundary condition on y and z, the resistive tearing mode instability is investigated with Harris sheet equilibrium.
- 5. Working on nonlinear tearing mode saturation and drift-kinetic electrons.